



17<sup>TH</sup> ADVANCED BEAM DYNAMICS WORKSHOP ON

**FUTURE LIGHT SOURCES**

# Advanced Insertion Device Practices and Concepts

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# **Advanced Insertion Device Practices and Concepts**

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Harima RIKEN, SPring-8**

**1. Motivation to develop insertion devices?**

**2. In-vacuum undulators**

**3. Examples of in-vacuum undulators**

**4. Advanced in-vacuum undulators**

**5. A new concept of SR facility**

# Motivation to develop insertion devices?

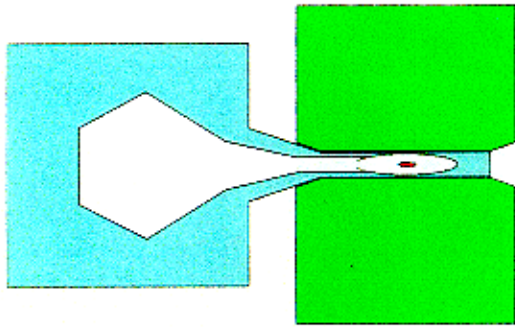
## 1. Various polarization characteristics

helical, elliptical, vertical, *Figure-8*

## 2. Higher-energy radiation

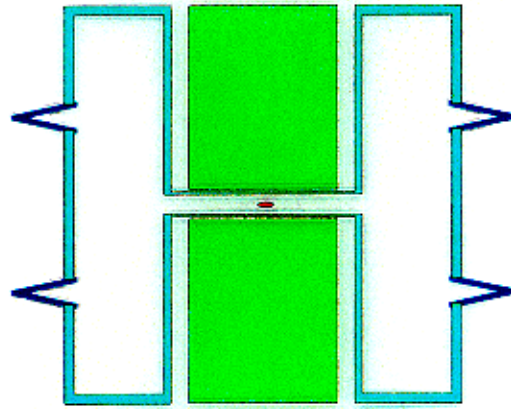
superconducting wiggler

short-period undulator → short magnetic  
gap



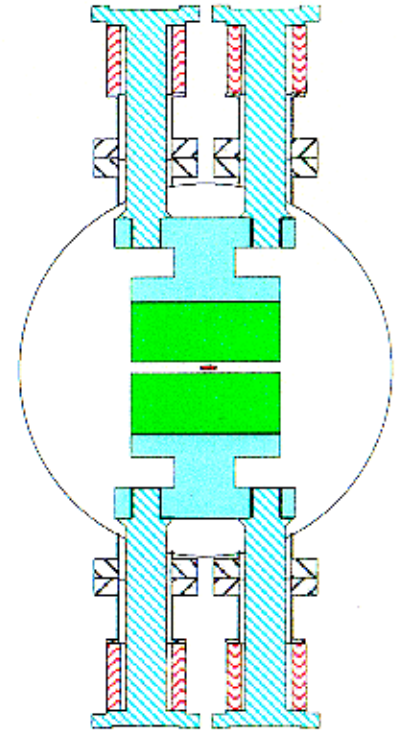
## Out-of-Vacuum

- x Thickness of the chamber wall
- x Conservative gap-height margin for injection or unordinary operation of the ring



## Flexible

- o Flexibility against any operation of the ring
- x Thickness of the chamber wall
- x Long devices?



## In-Vacuum

- o Flexibility against any operation of the ring
- o Vacuum gap = magnet gap
- o Long devices
- x Difficulty in making devices UHV?
- demagnetization

# Development of In-Vacuum Undulators

## Delicate undulator magnet system

should be compatible with **Ultrahigh Vacuum (UHV)**.

○ Outgassing from permanent magnets ?

**TiN** coating

○ Demagnetization due to UHV bakeout?

**Permanent magnets with very high coercivity at high temperature (140°C)**

○ clamping?

○ Shimming?

small magnet chips

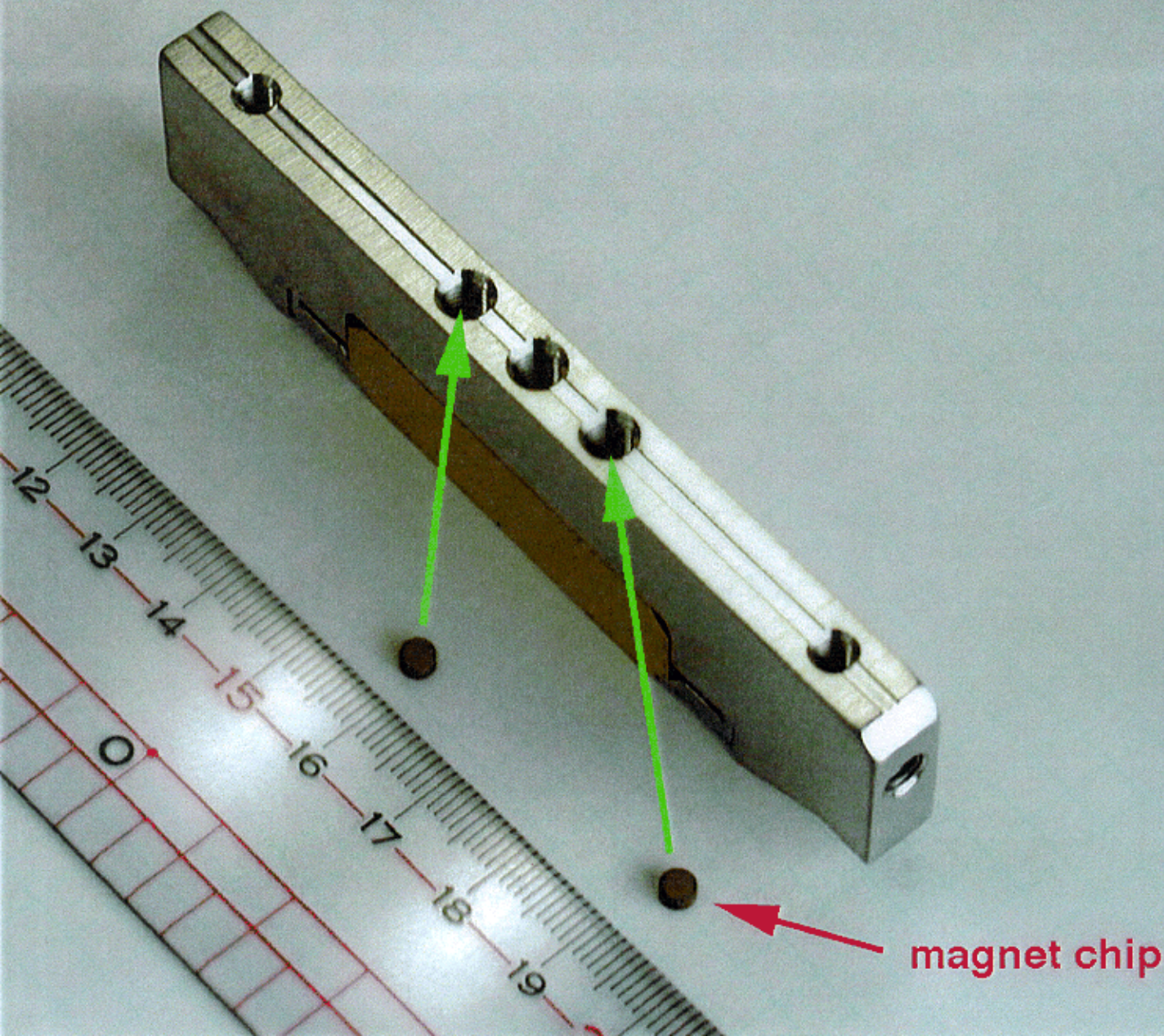
## Heating problem by image beam current

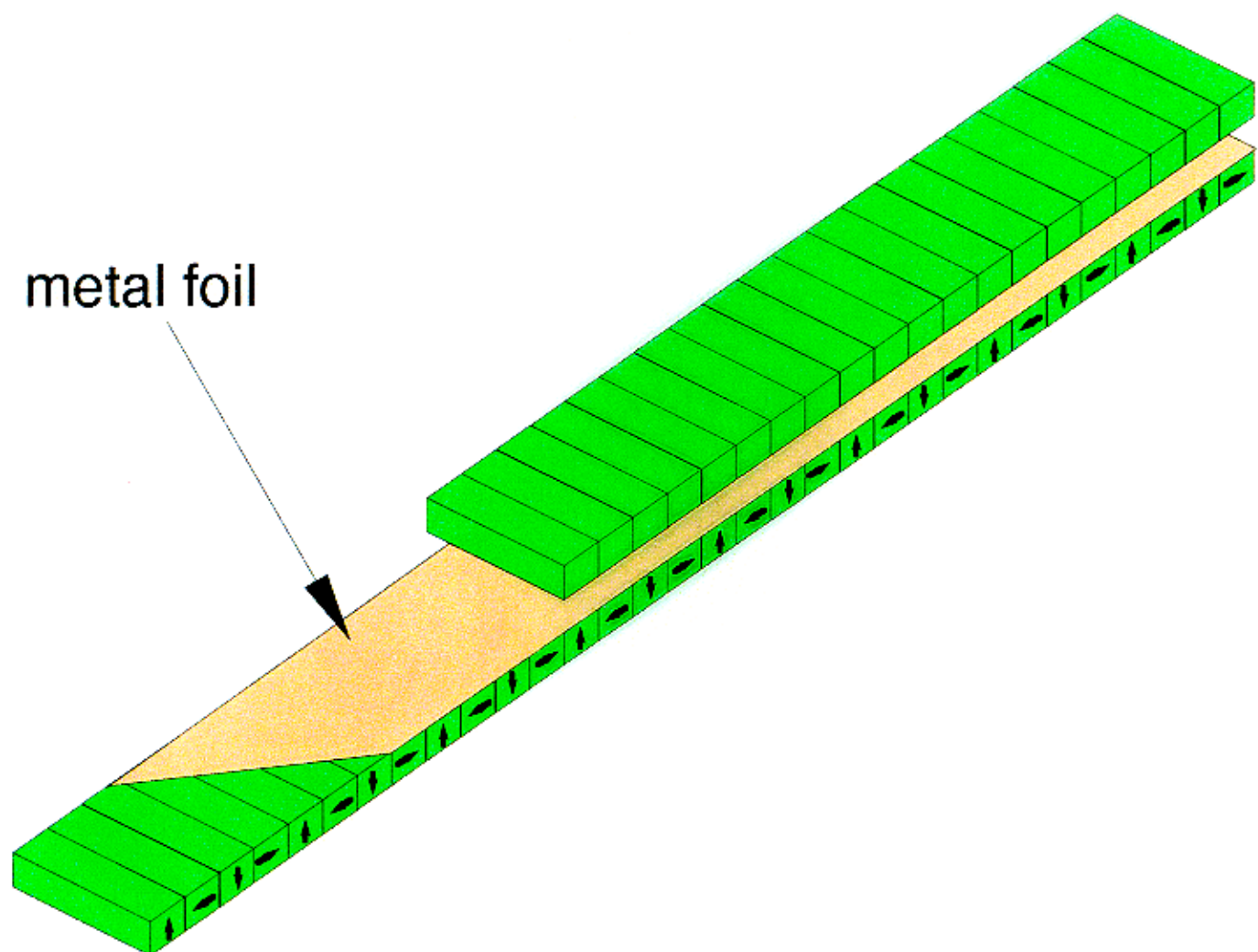
Solution;

Cu-plated Ni foils for magnet cover

Water-cooled rf-finger







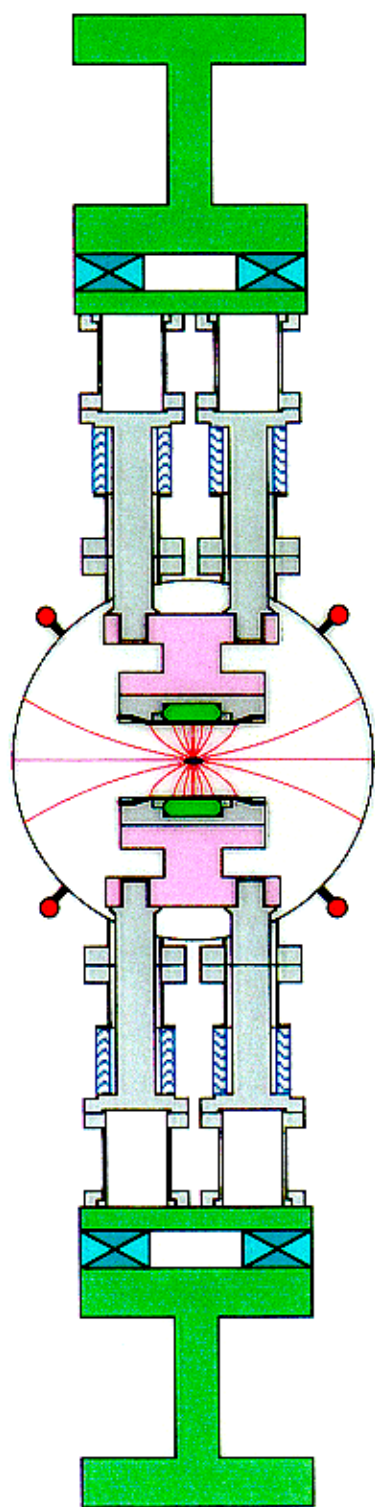
metal foil

Magnet Cover

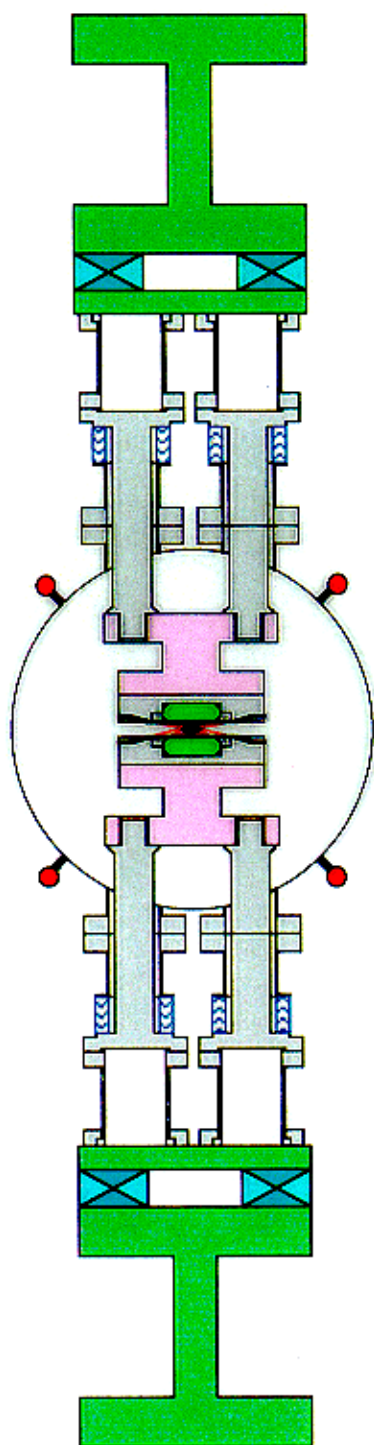


# Image current heating

$$P \propto \frac{1}{Gap}$$



G=50mm

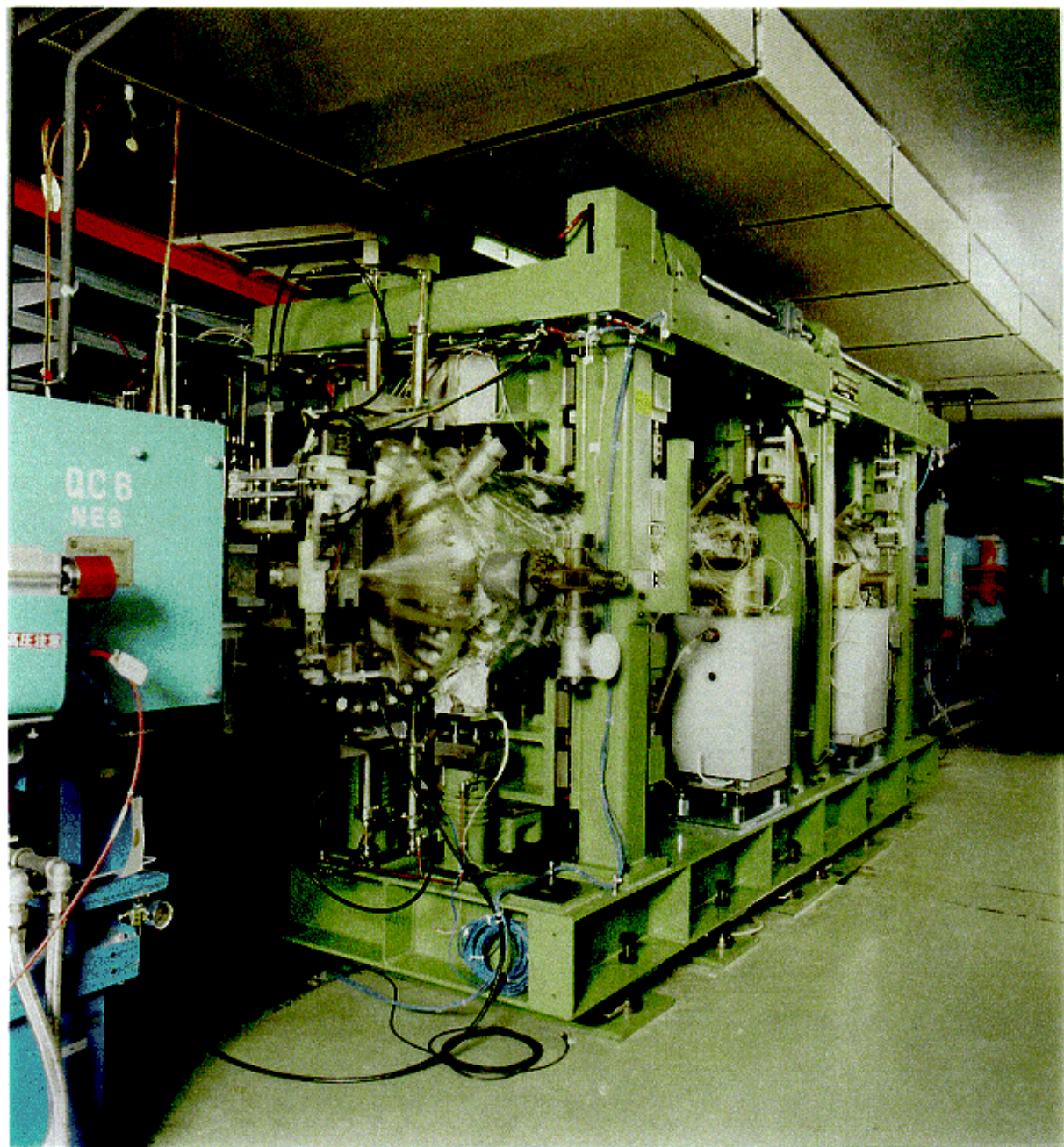


G=10mm

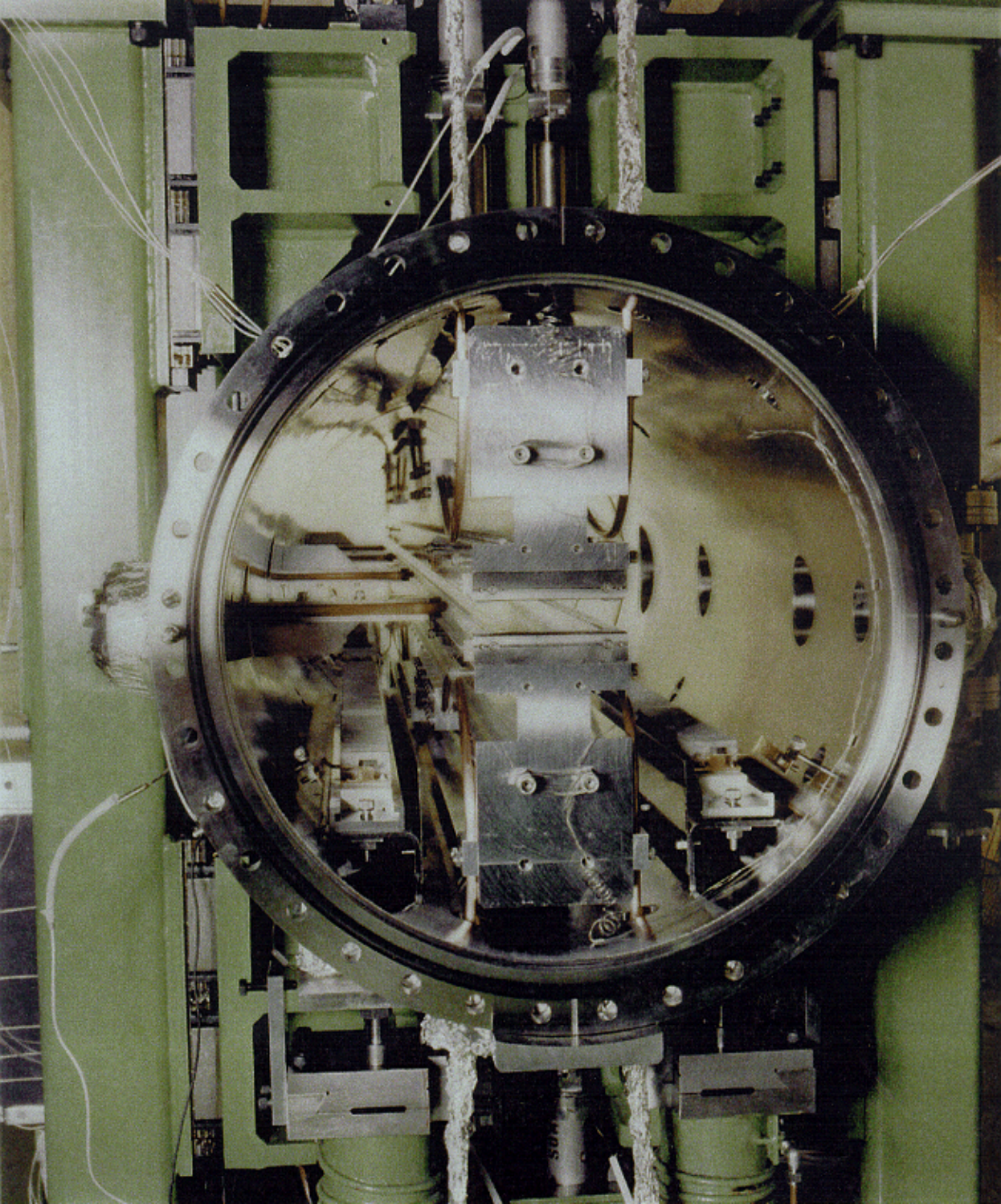


KEK (1990)

$\lambda_u = 4\text{ cm}$ ,  $N = 90$ ,  $G_{\min} = 10\text{ mm}$







## In-vacuum undulators installed at SPring-8

### Standard type

| $\lambda_u(\text{mm})$ | N   | $G_{\min}(\text{mm})$ | $B_{\max}(\text{T})$ | $K_{\max}$ | total # |
|------------------------|-----|-----------------------|----------------------|------------|---------|
| 32                     | 140 | 8                     | 0.84                 | 2.5        | 8       |
| 40                     | 112 | 13                    | 0.59                 | 2.2        | 1       |

### Hybrid type(+permendur)

| $\lambda_u(\text{mm})$ | N   | $G_{\min}(\text{mm})$ | $B_{\max}(\text{T})$ | $K_{\max}$ | total # |
|------------------------|-----|-----------------------|----------------------|------------|---------|
| 24                     | 187 | 5                     | 0.9                  | 2.2        | 1       |

### Vertical undulator

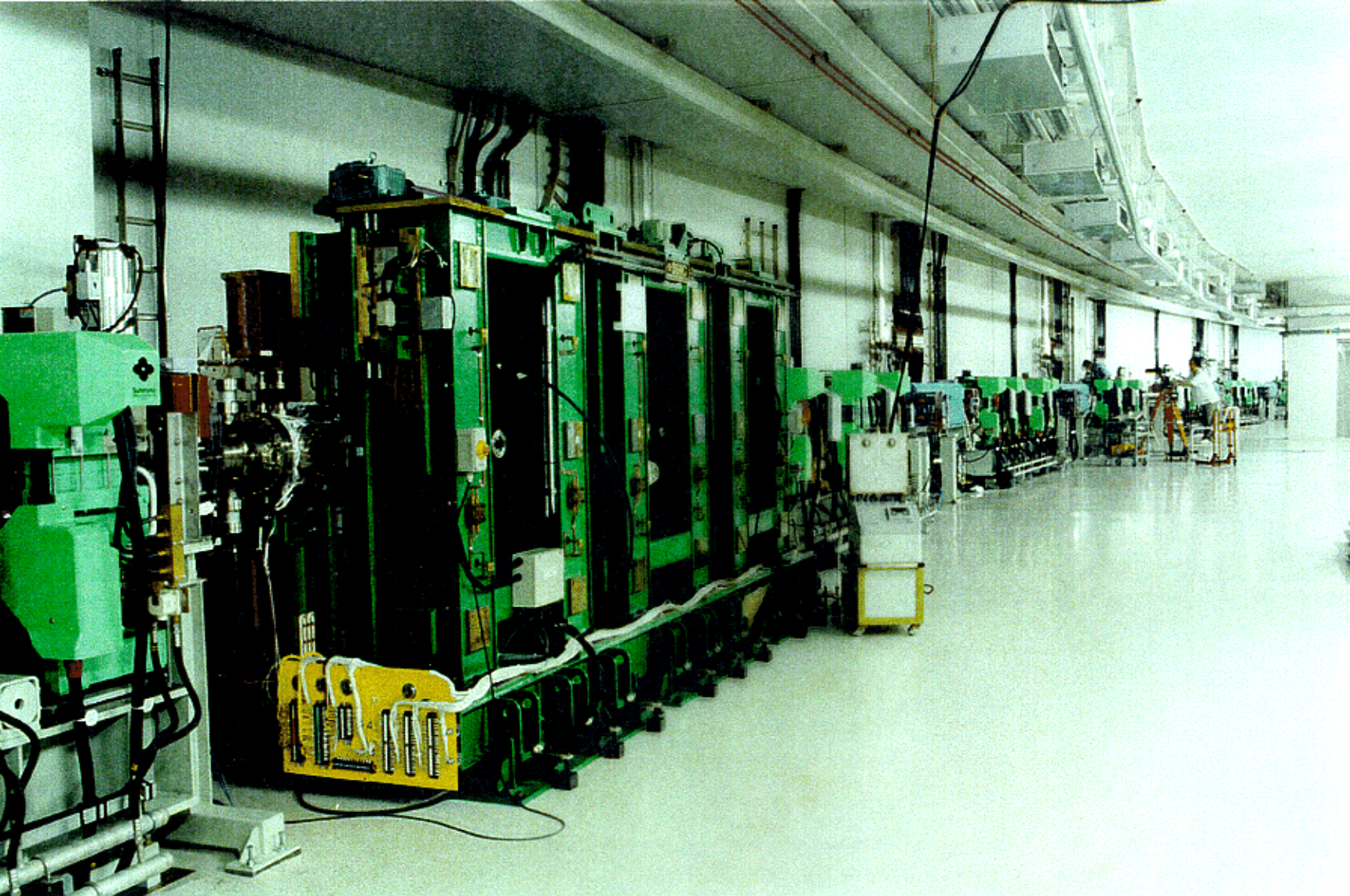
| $\lambda_u(\text{mm})$ | N    | $G_{\min}(\text{mm})$ | $B_{\max}(\text{T})$ | $K_{\max}$ | total # |
|------------------------|------|-----------------------|----------------------|------------|---------|
| 37                     | 2x37 | 8                     | 0.5                  | 1.7        | 1       |

### Figure-8 undulator

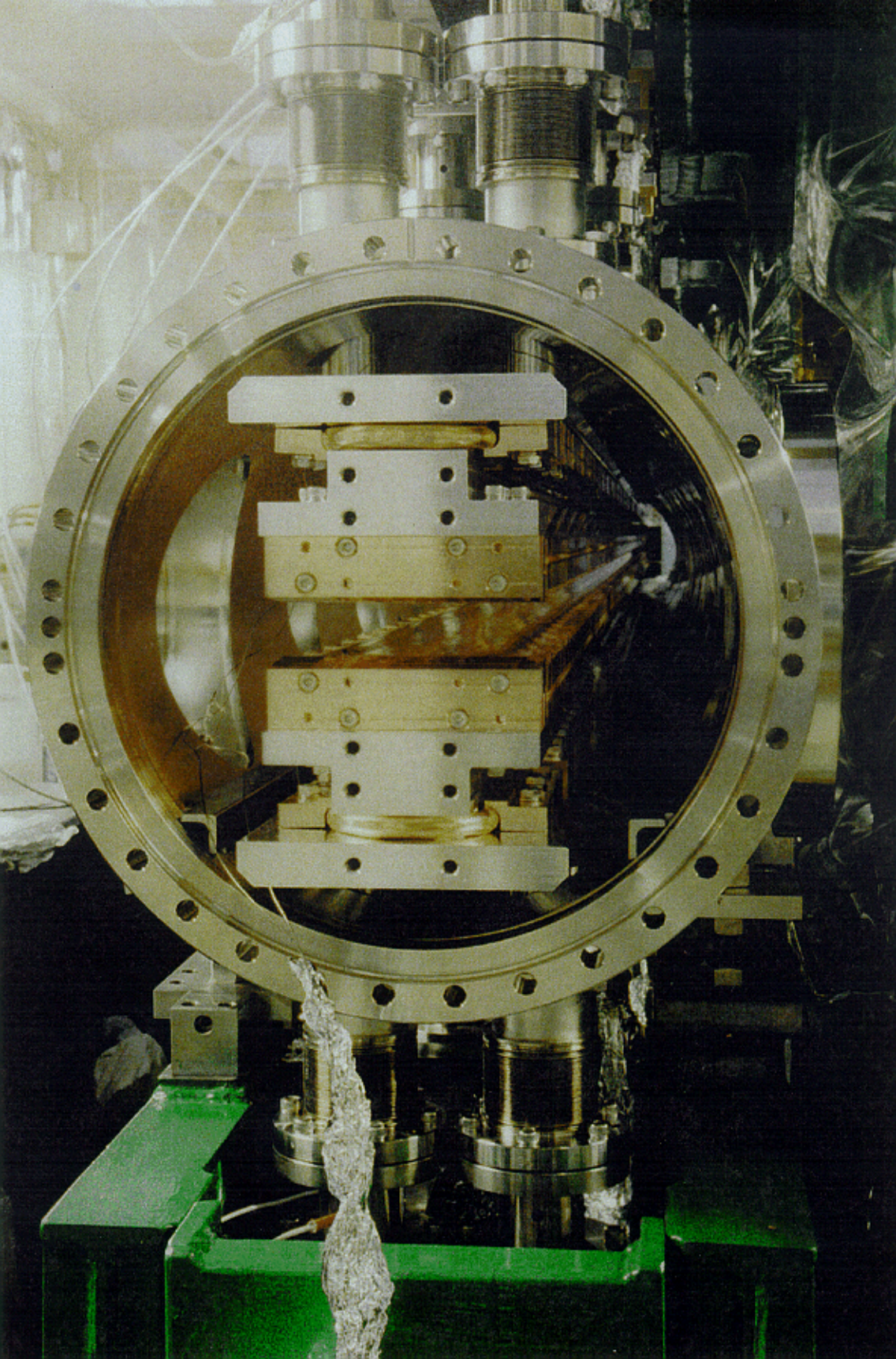
| $\lambda_u(\text{mm})$ | N   | $G_{\min}(\text{mm})$ | $B_{\max}(\text{T})$ | $K_{\max}$ | total # |
|------------------------|-----|-----------------------|----------------------|------------|---------|
| 26                     | 172 | 5                     | 1.05                 | 2.6        | 1       |
|                        |     |                       | 0.34                 | 1.7        |         |

**Out-of-vacuum type: 4 devices**



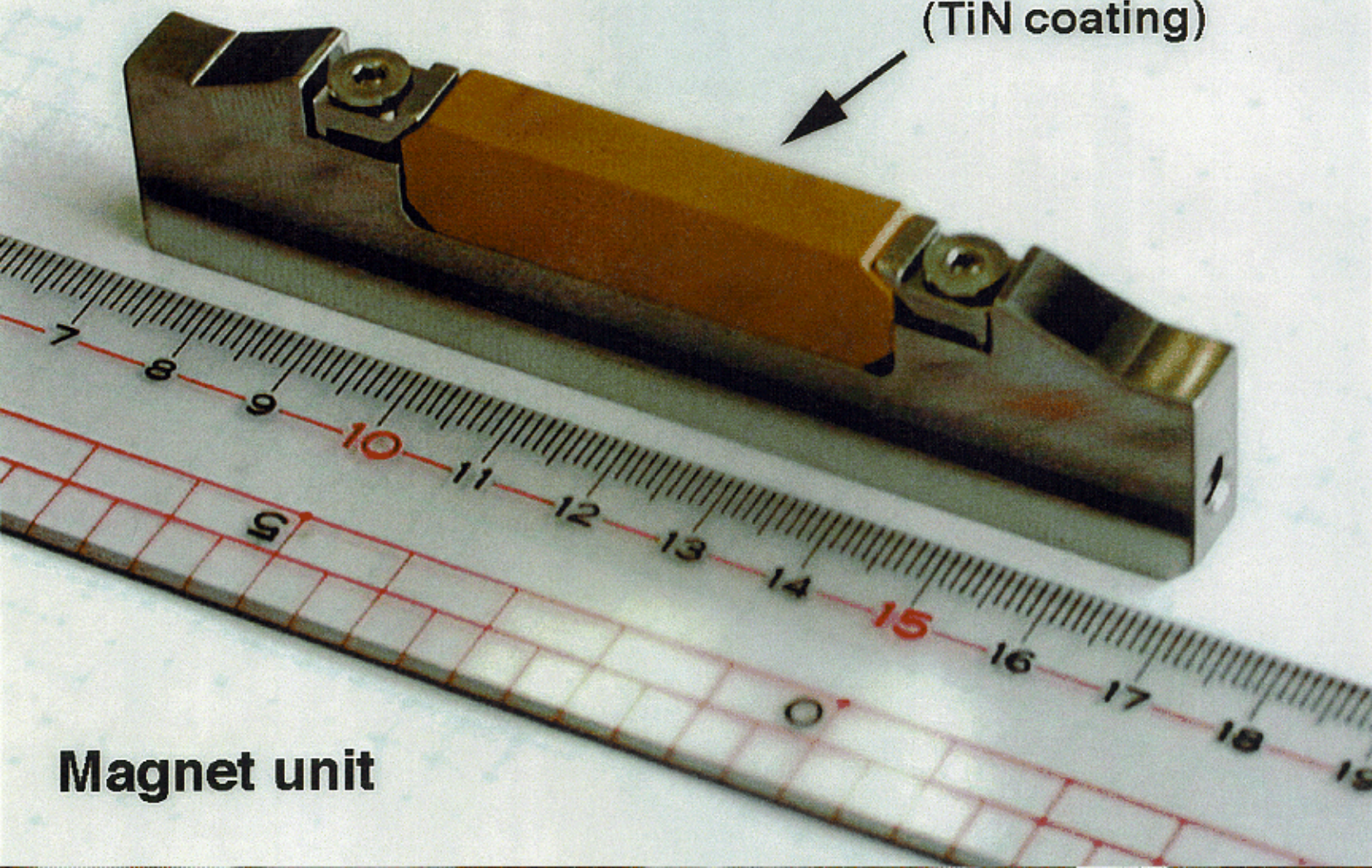






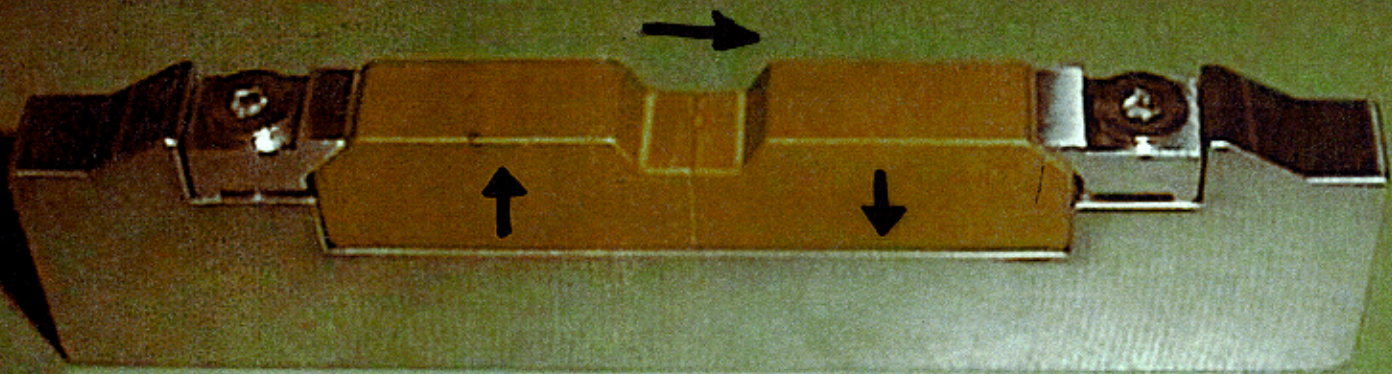


NdFeB magnet  
(TiN coating)

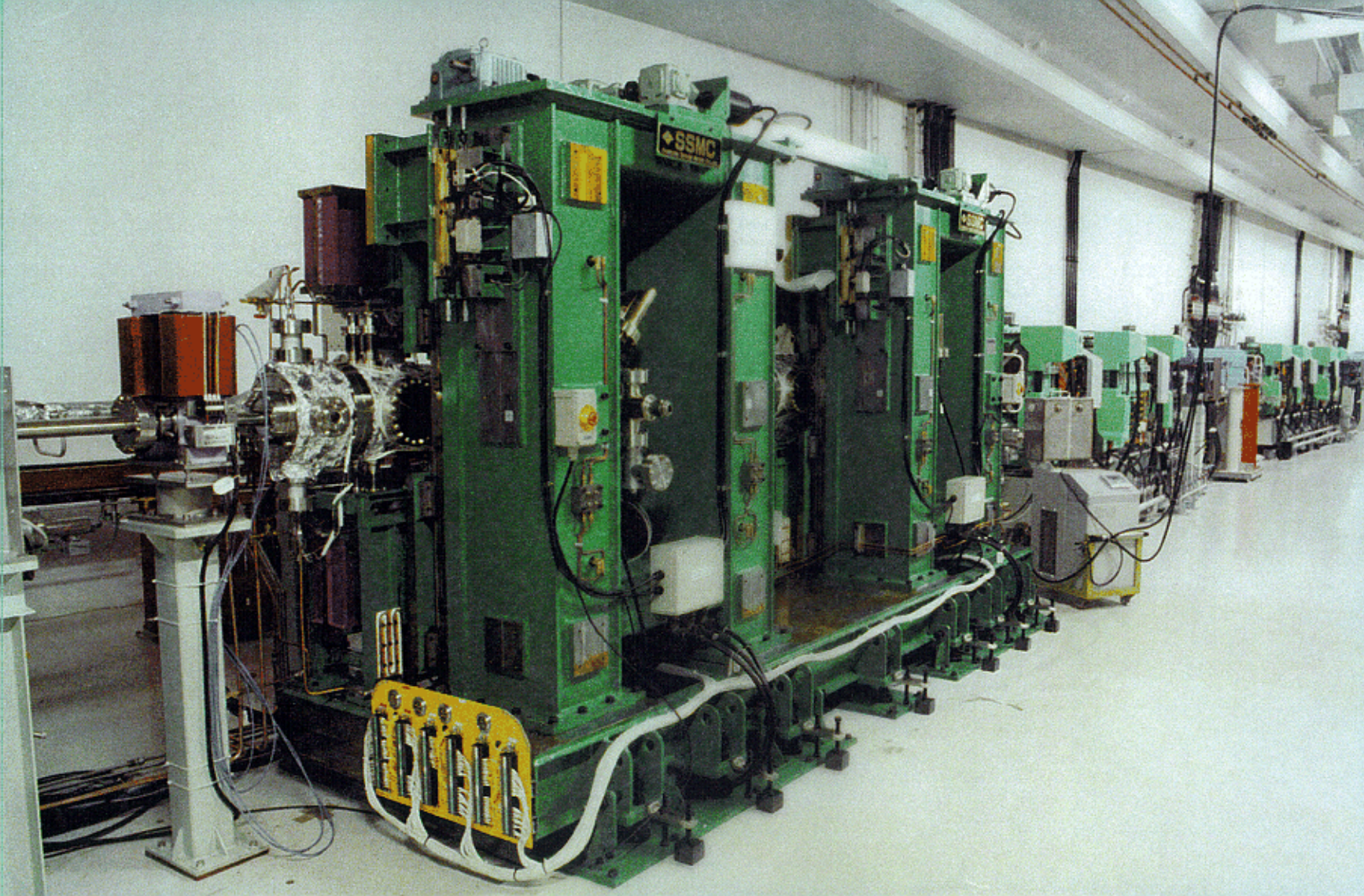


Magnet unit

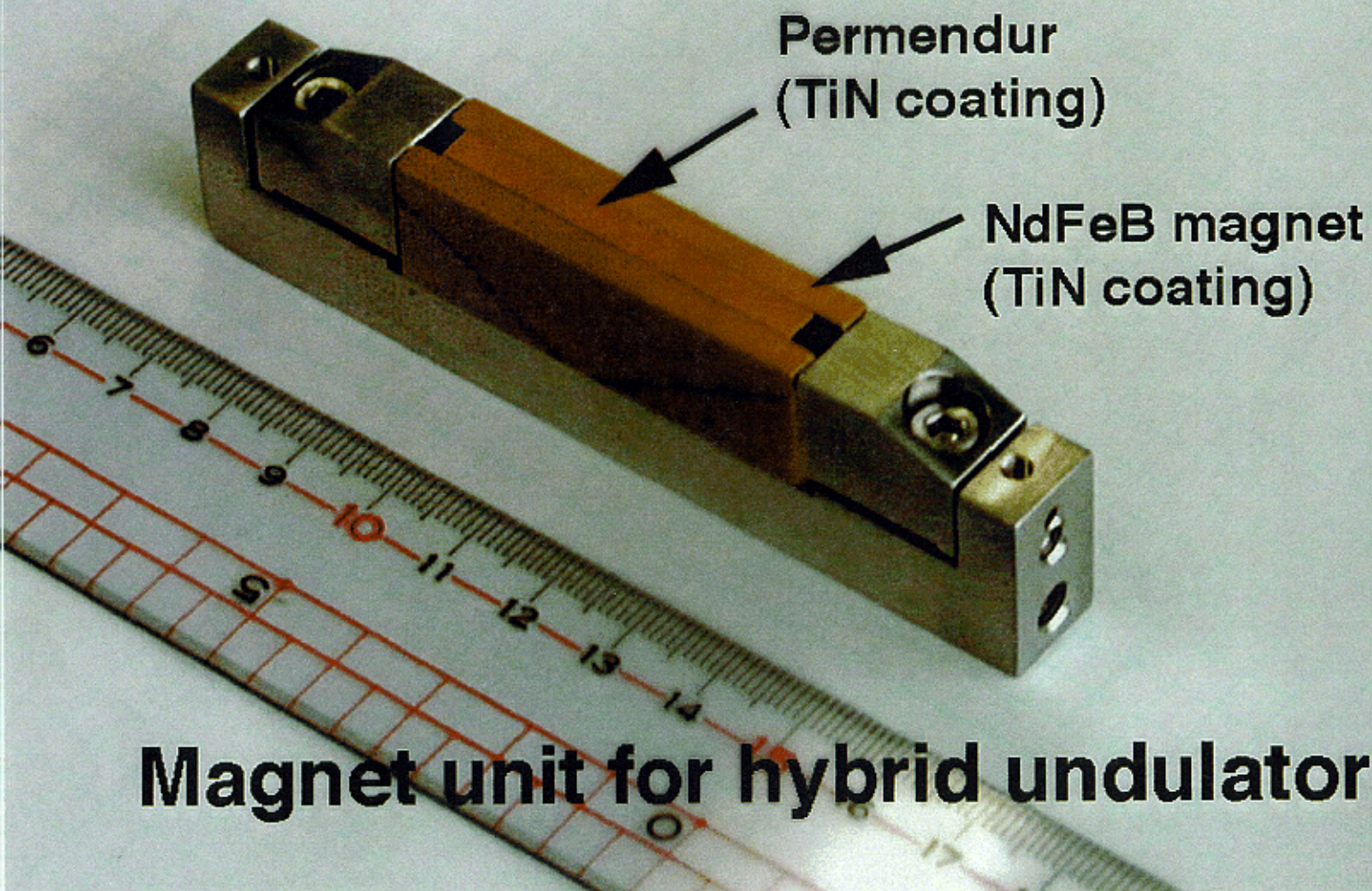










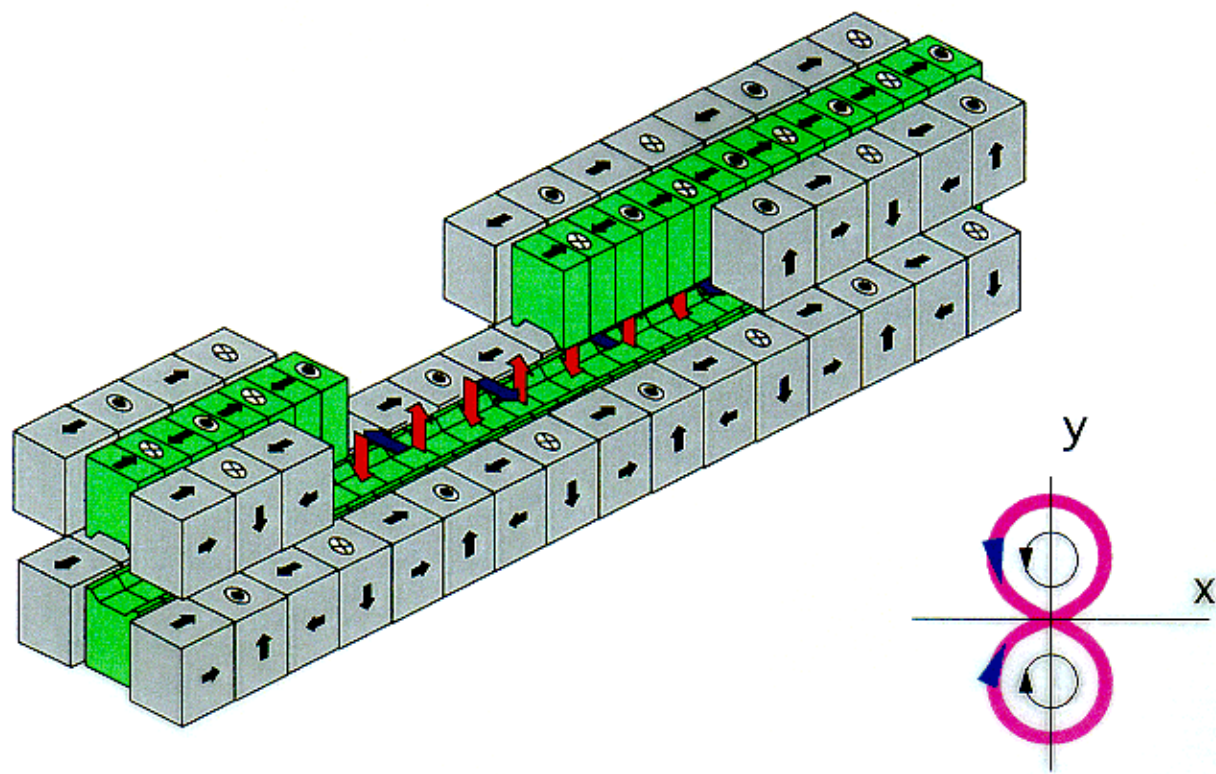


Permendur  
(TiN coating)

NdFeB magnet  
(TiN coating)

**Magnet unit for hybrid undulator**

## Figure-8 Undulator



For soft x-ray region

$$\lambda_u = 100\text{mm}, N = 45, G_{\min} = 30\text{mm}$$

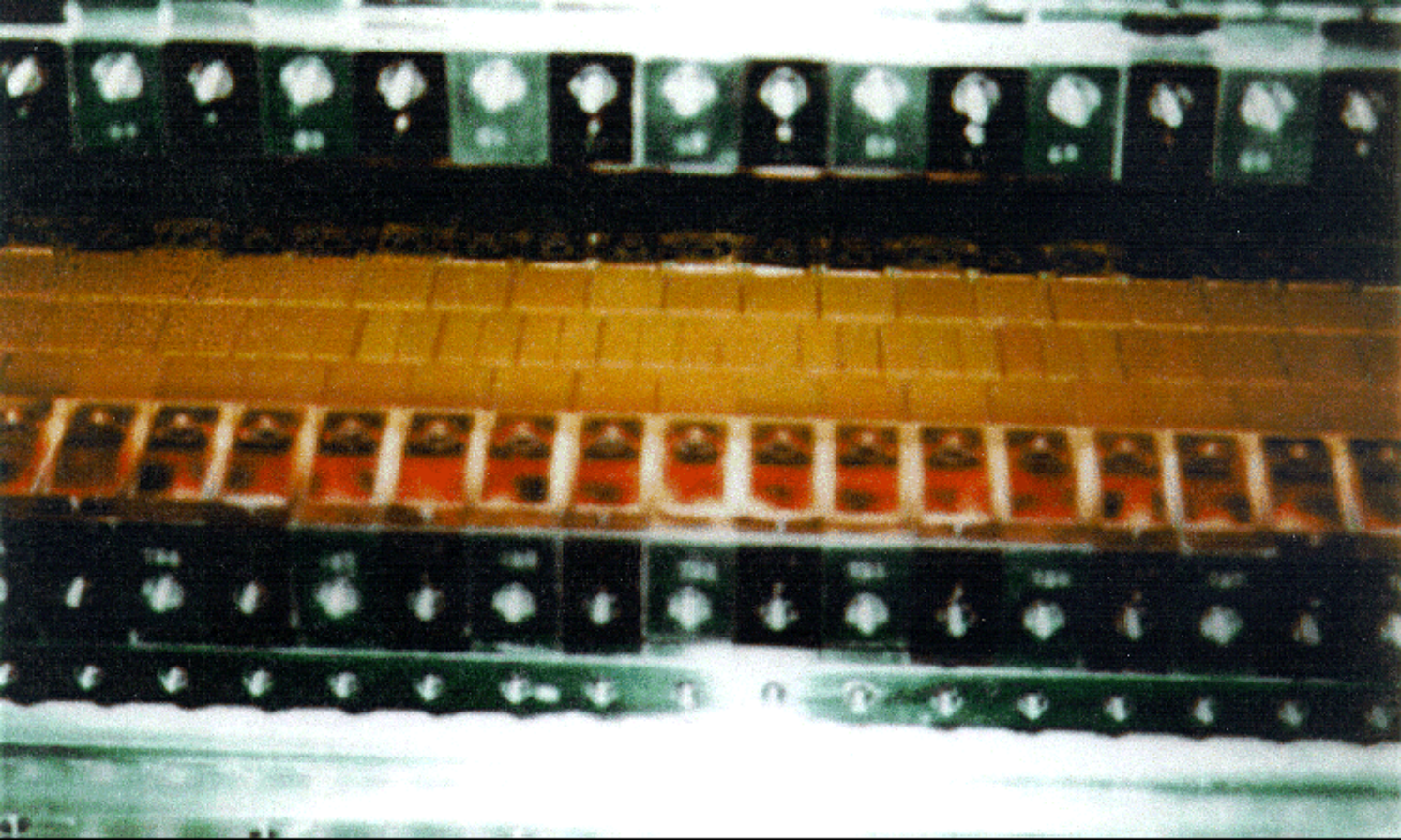
$$B_{v\max} = 0.73\text{T}, B_{h\max} = 0.23\text{T}$$

For x-ray region (in-vacuum)

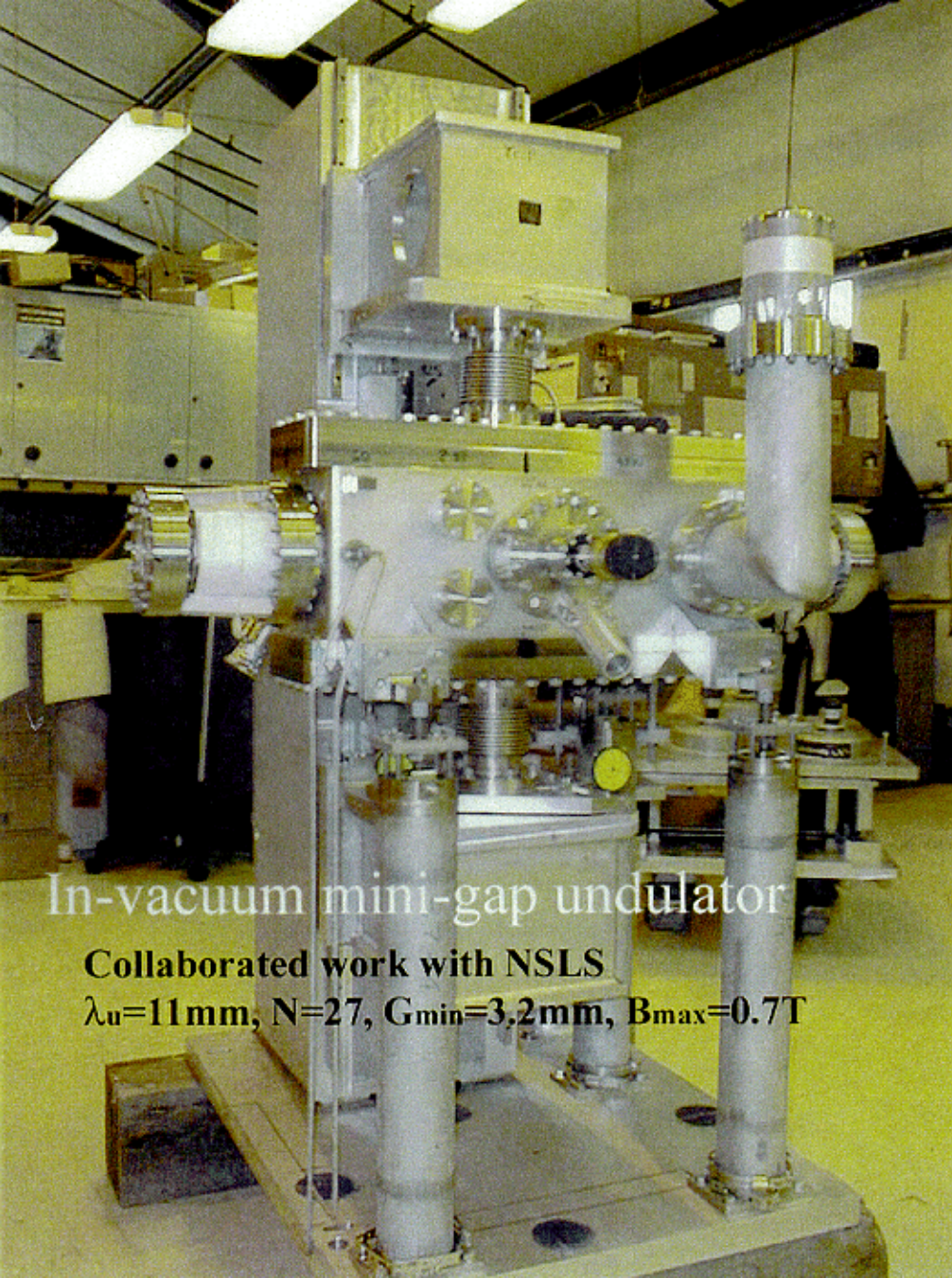
$$\lambda_u = 26\text{mm}, N = 171, G_{\min} = 5\text{mm}$$

$$B_{v\max} = 0.99\text{T}, B_{h\max} = 0.30\text{T}$$







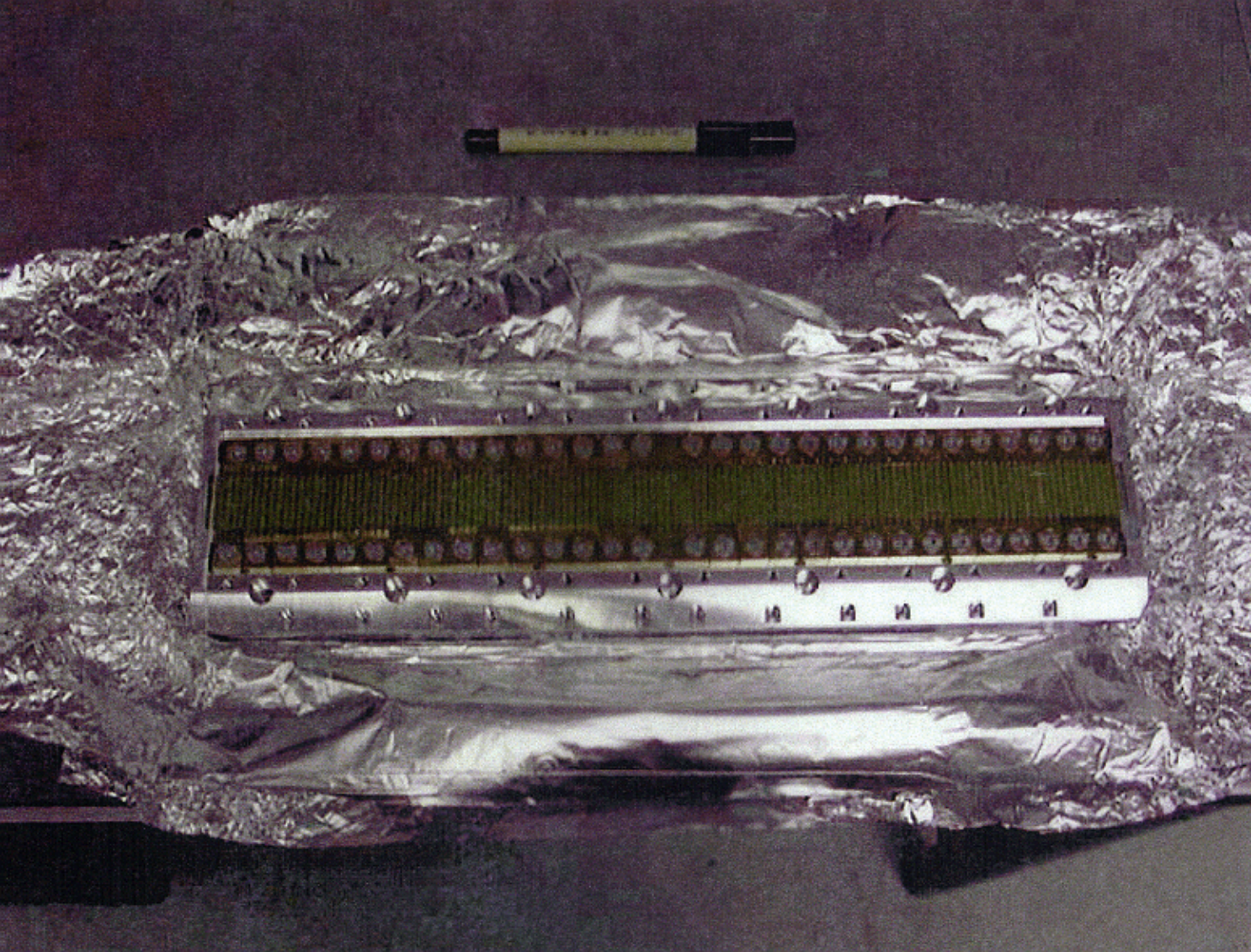


In-vacuum mini-gap undulator

**Collaborated work with NSLS**

$\lambda_u=11\text{mm}$ ,  $N=27$ ,  $G_{\text{min}}=3.2\text{mm}$ ,  $B_{\text{max}}=0.7\text{T}$







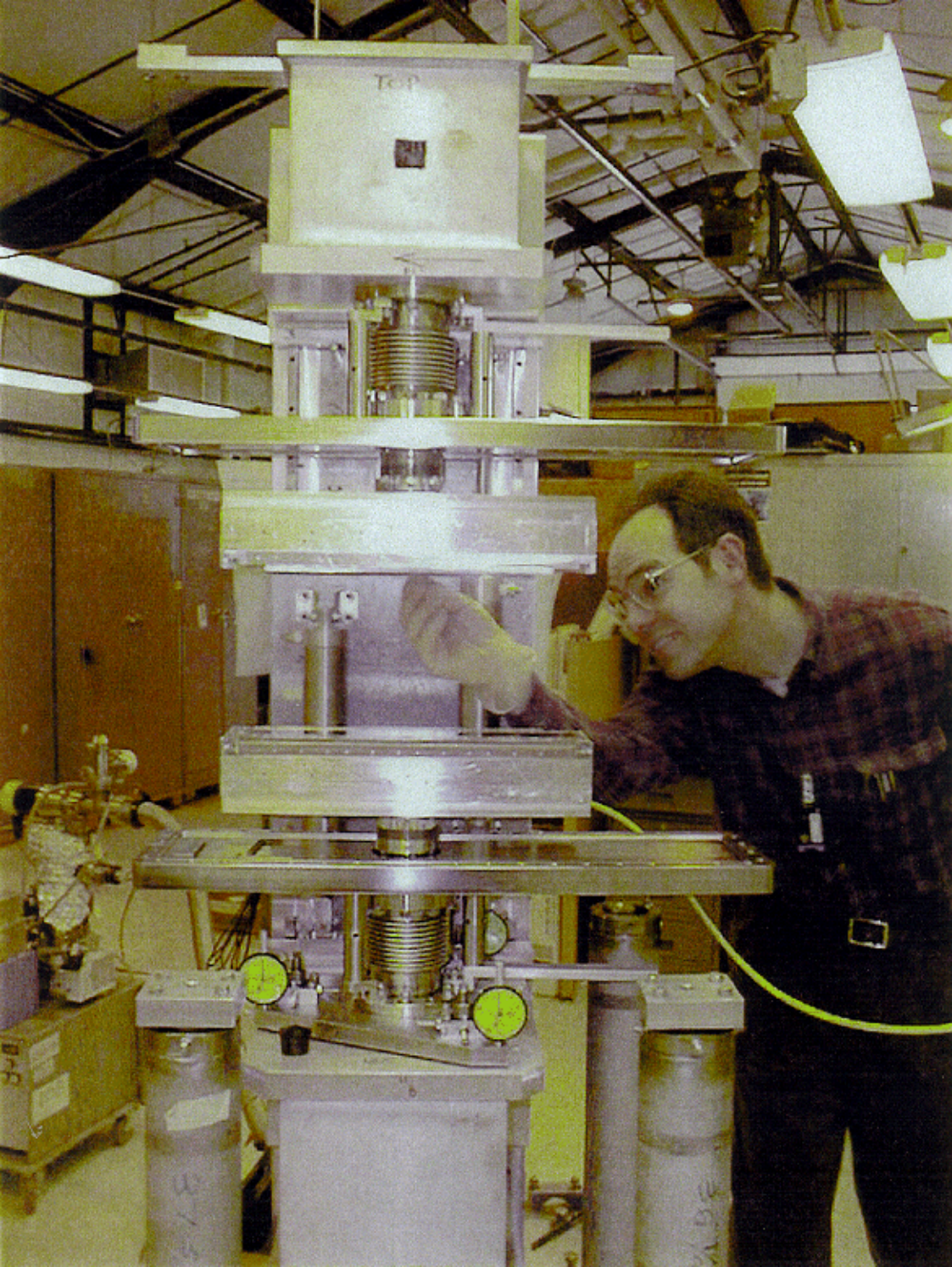
役 B

A

gap = 4.5 mm  
~~22~~ 22 mm  
30

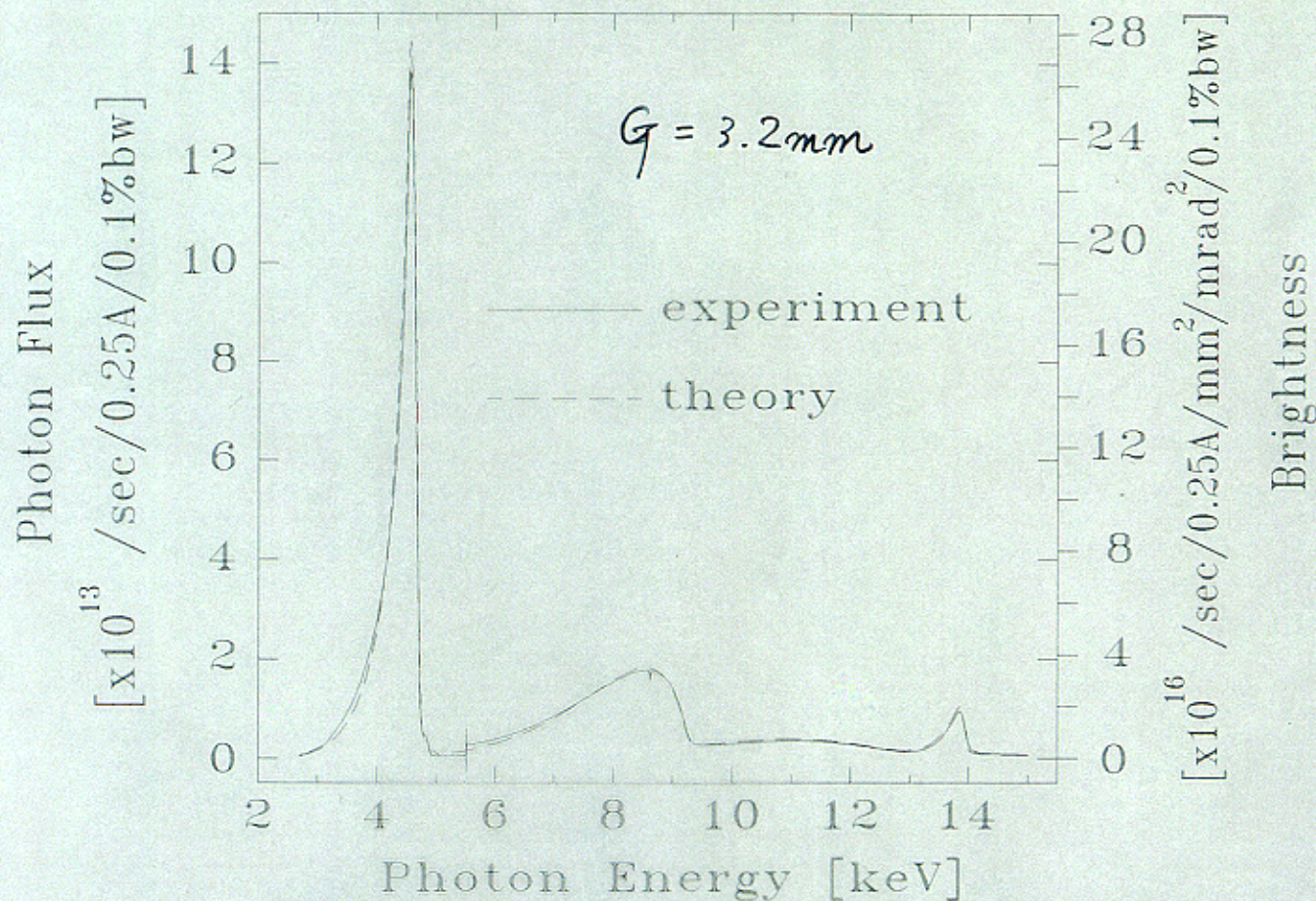








# *Spectrum from the In Vacuum Undulator* *IVUN at 2.584 GeV*





# Special in-vacuum devices under construction

## In-vacuum helical undulator

$$\begin{aligned}L &= 4.5\text{m}, G_{\min} = 7\text{mm} \\ \lambda_u &= 36\text{mm} (N = 125) \\ B_{\max} &= 0.33\text{T}\end{aligned}$$

## In-vacuum revolver undulator of mini-gap type

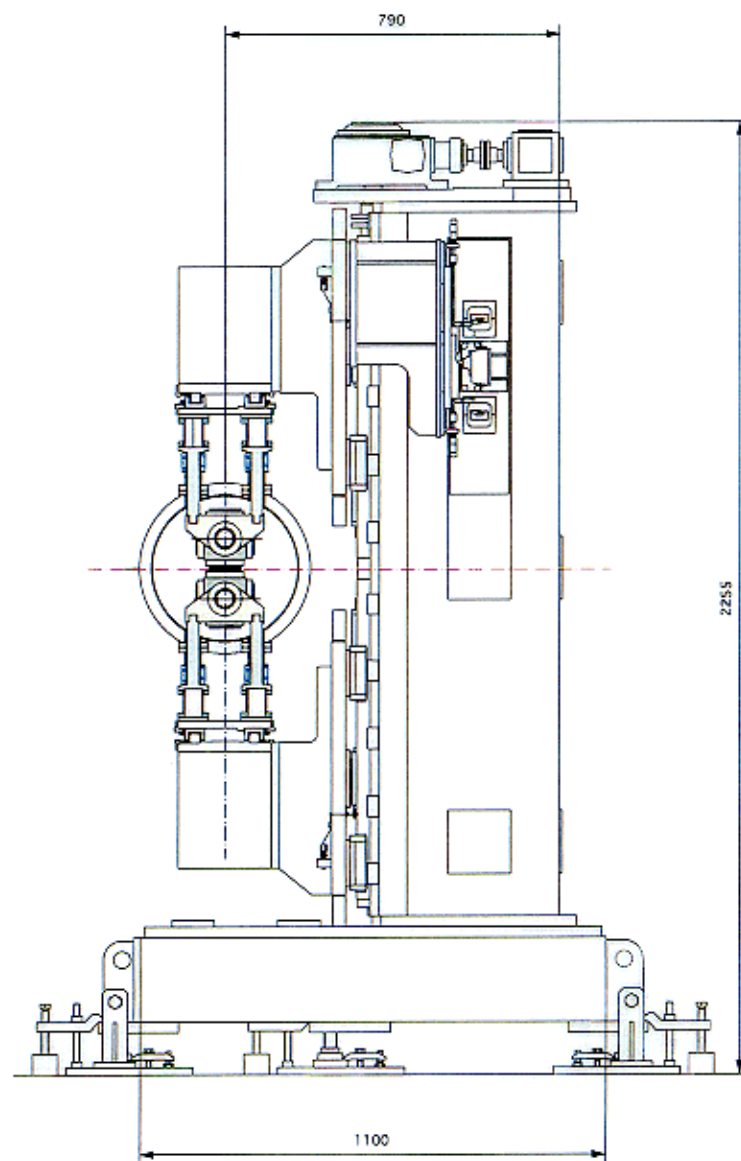
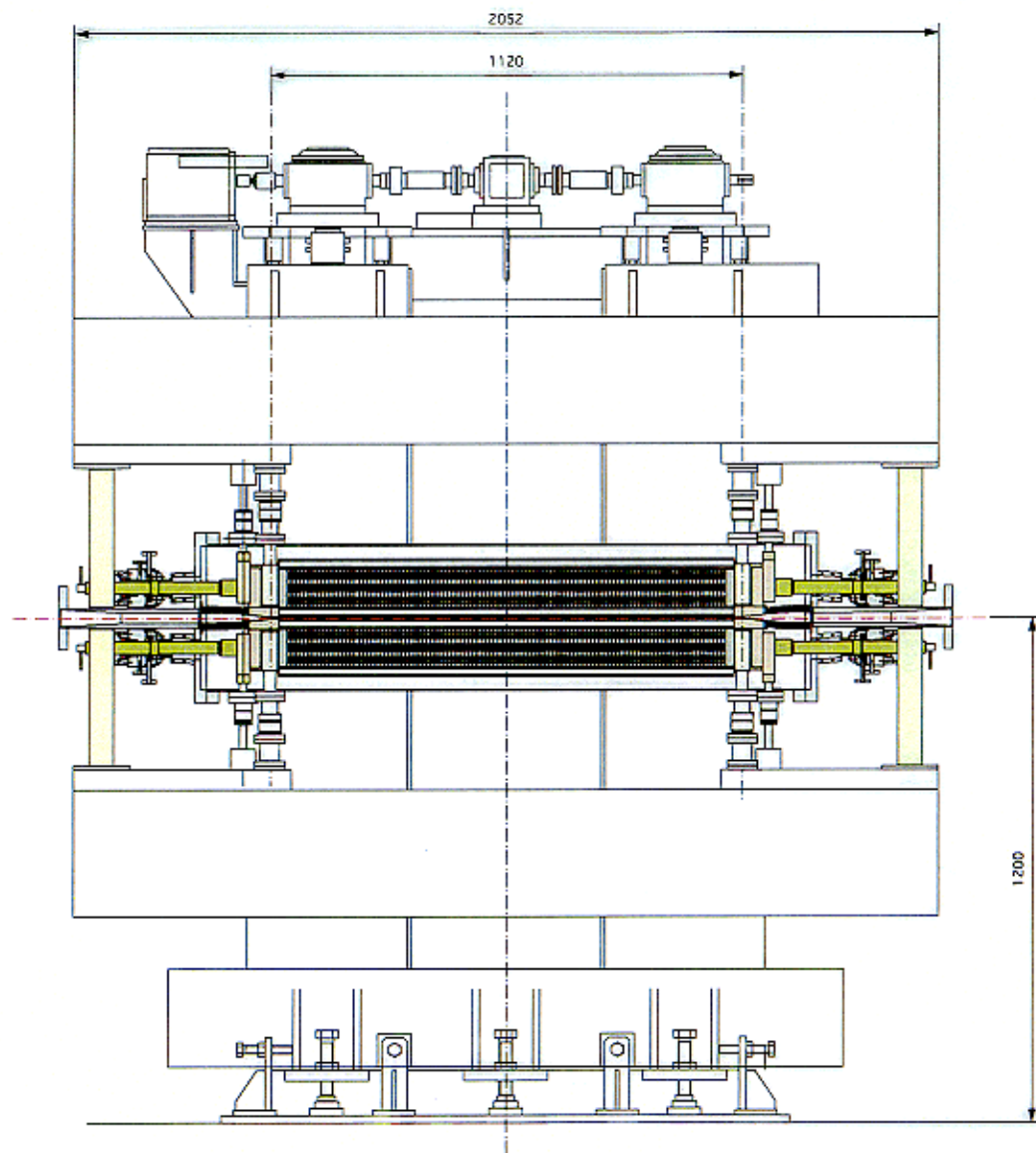
$$\begin{aligned}L &= 1\text{m}, G_{\min} = 2\text{mm} \\ \text{4-undulator system} \\ \lambda_u &= 6\text{mm}(N = 173), \quad 10\text{mm}(N = 104), \\ &\quad 15\text{mm}(N = 69), \quad 20\text{mm}(N = 51) \\ &\text{additional magnet arrays to reduce magnetic load}\end{aligned}$$

## In-vacuum high-field wiggler

$$\begin{aligned}L &= 4.5\text{m}, G_{\min} = 7\text{mm} \\ \lambda_u &= 100\text{mm} (N = 45) \\ B_{\max} &= 2\text{T}\end{aligned}$$

## Very long in-vacuum undulator

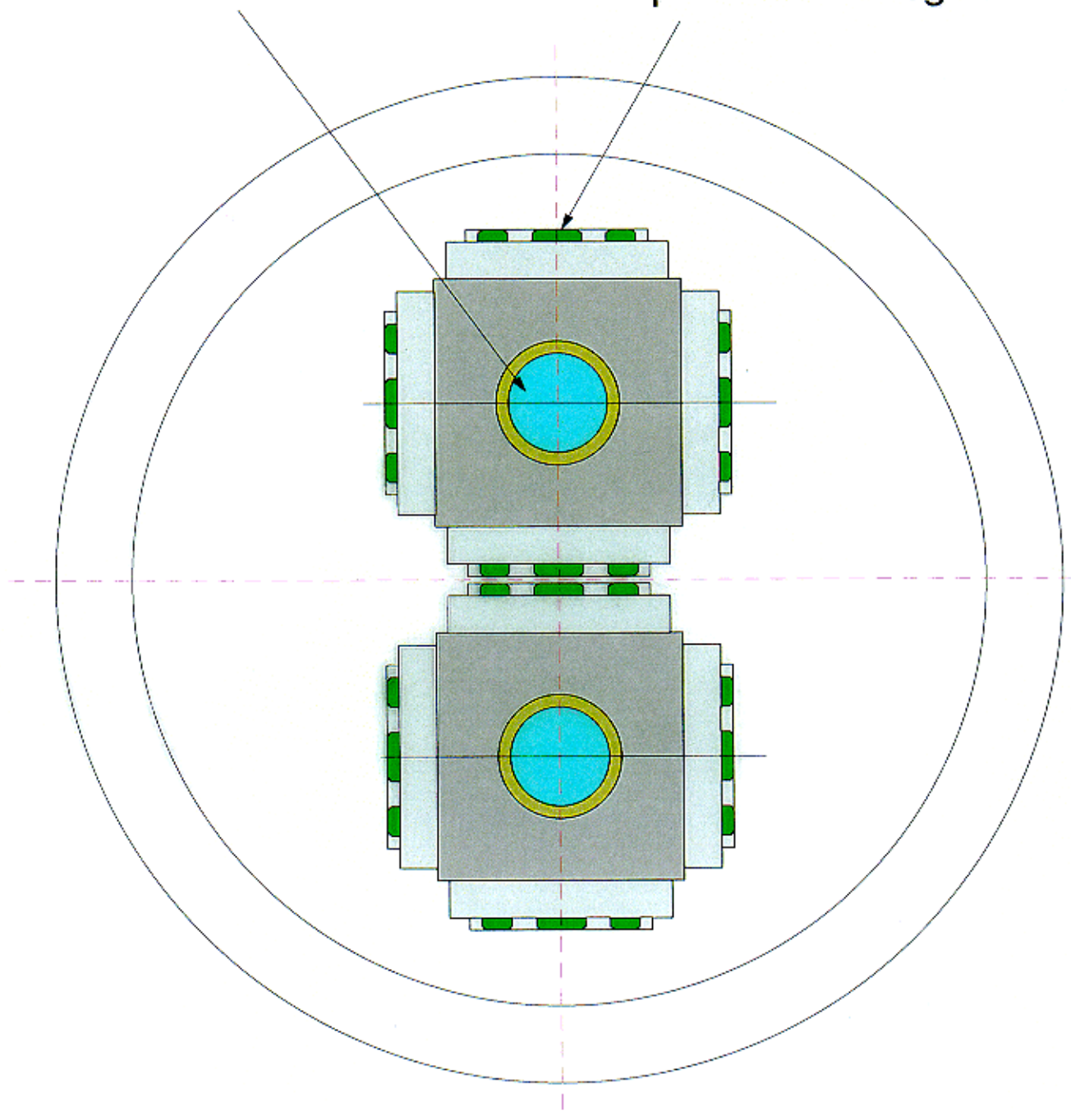
$$\begin{aligned}L &= 25\text{m}, G_{\min} = 12\text{mm} \\ \lambda_u &= 32\text{mm} (N = 781) \\ B_{\max} &= 0.57\text{T}\end{aligned}$$



In-vacuum Revolver Undulator

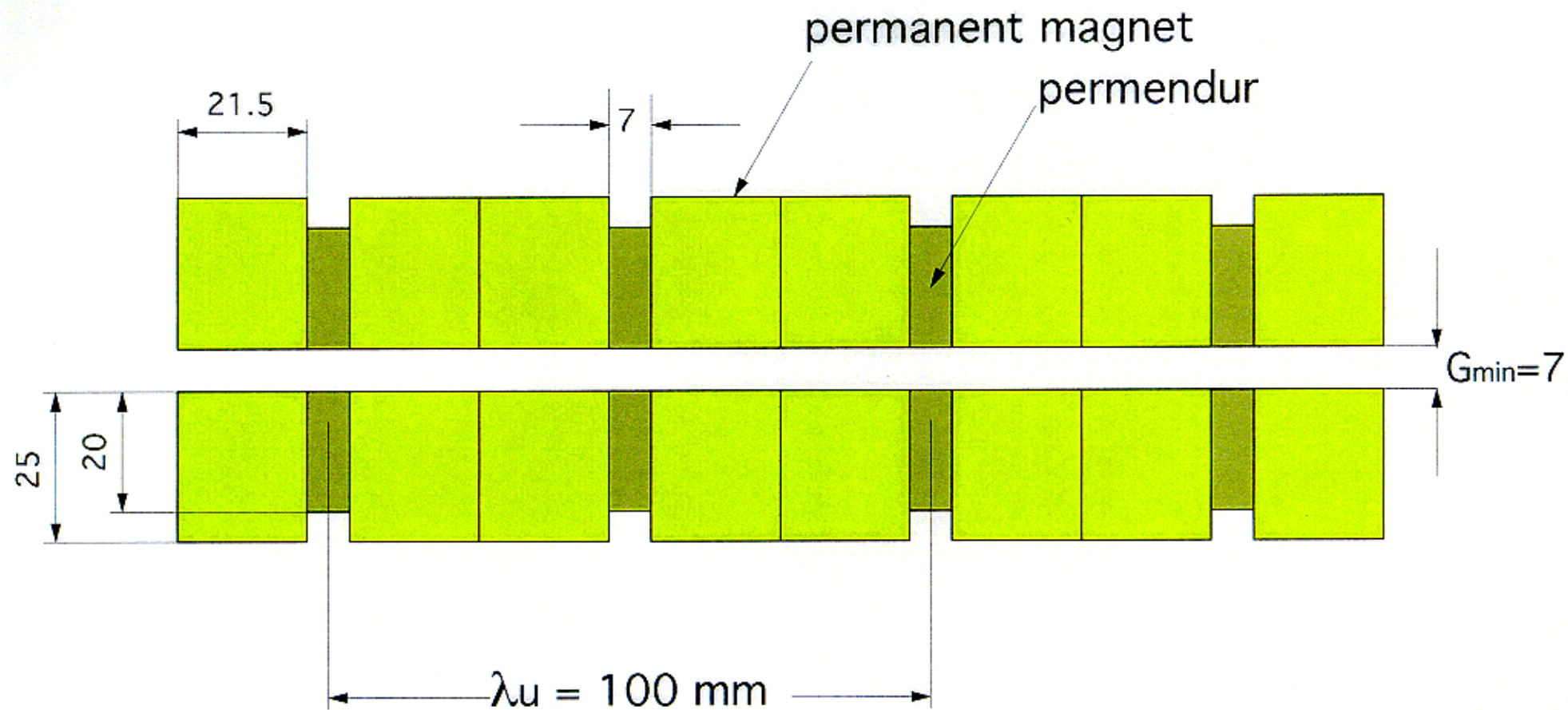
cooling water

permanent magnet



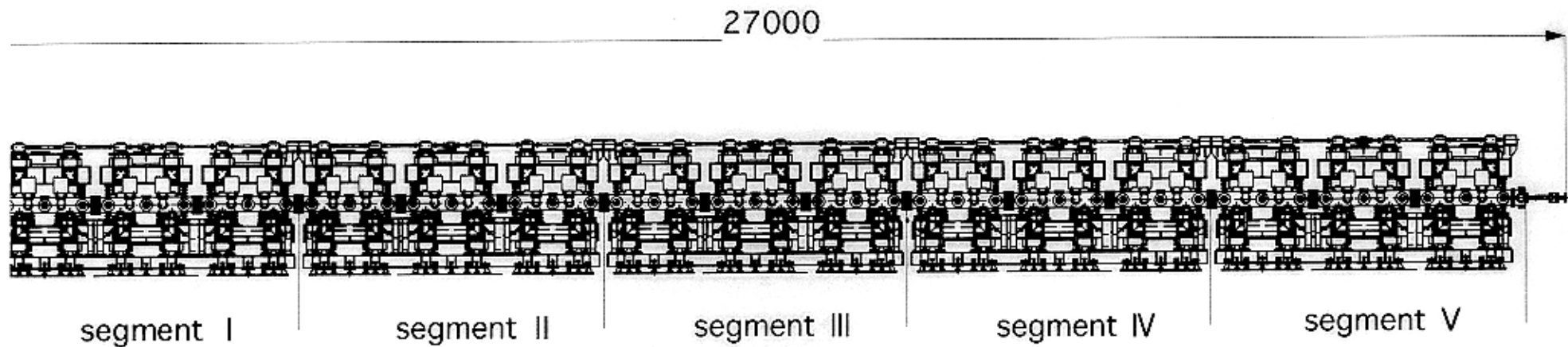
In-vacuum Revolver Undulator





In-vacuum high field wiggler  
 $\lambda_u = 100 \text{ mm}$ ,  $N = 45$ ,  $B_{max} = 2 \text{ T}$   
 $\epsilon_c = 85 \text{ keV}$





Very long in-vacuum undulator  
 $L=25\text{m}$ ,  $\lambda_u=32\text{mm}$ ,  $N=781$   
 $G_{\min}=12\text{mm}$ ,  $B_{\max}=0.57\text{T}$

## In-vacuum mini-gap undulators



### New concept of SR facility

Moderate-cost and medium-sized facility with a combination of a low emittance ring and very short gap undulators.

Performance:

comparable to that of APS, ESRF or SPring-8

### Examples

#### Swiss Light Source

$E = 2.5\text{GeV}$ ,  $I = 400\text{ mA}$ ,  $\varepsilon = 3\text{ nm}\cdot\text{rad}$

Totally 12 straight sections

6 straight sections for (in-vacuum) mini-gap devices

#### Australian Light Source

